

# Introduction to Delay-Differential Equations

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but in general there is no explicit formula for the solution.

Delay-differential equations:

$$\dot{x}(t) = f(x(t), x(t - r)),$$

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Delay-differential equations (delay equations) arise as mathematical models in many areas of science and engineering.



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(finite speed of signal transmission)

Multiple delays:

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Nonautonomous systems, variable delays ( $r = r(t)$  or  $r = r(x(t))$ ), infinite delays, . . .

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$$\dot{x} = Ax$$

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One can find solutions of the form  $x(t) = e^{\lambda t}v$  where

$$(\lambda I - A - Be^{-\lambda r})v = 0, \quad \text{and}$$

$$\Delta(\lambda) = \det(\lambda I - A - Be^{-\lambda r}) = 0.$$

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In this sense, a delay equation is infinite-dimensional.

The nonlinear **Mackey-Glass equation** arises as a model of blood cell population:

$$\dot{x}(t) = -ax(t) + g(x(t-r)), \quad g(x) = \frac{bx}{1+x^k}$$

where  $a, b, r > 0$  and  $k > 1$ .

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Note: The same equation, with a different  $g$ , arises in nonlinear optics.

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## Wright's Equation

$$\dot{x}(t) = -\alpha x(t-1)[1+x(t)]$$

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$$\dot{x}(t) = f(x(t), x(t-r))$$

one specifies an initial condition as

$$x_{t_0} = \varphi \in \mathcal{C}$$

where

$$\mathcal{C} = C([-r, 0], \mathbf{R}^n),$$

$x_t \in \mathcal{C}$  is given by  $x_t(\theta) = x(t + \theta)$  for  $\theta \in [-r, 0]$ .

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Then for every  $t \geq t_0$  one has  $x_t \in \mathcal{C}$  for the solution. Existence is for forward time only, and uniqueness is problematic for variable delays.

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- ▶ chaotic dynamics

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This program has been carried out quite successfully for problems with constant delay, but is still (actively!) underway for problems with variable delays.



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Similar result for the case of a variable delay  $r = r(x(t))$ , but little is known for multiple delays.



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$\|x\| = \sup_{t \in \mathbf{R}} |x(t)| \geq K > 0$  as  $\beta \rightarrow 0$  provided that either

- ▶  $r \equiv 1$  (constant delay);
- ▶  $r'(0) \neq 0$ ;
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Each case requires a different argument, and the asymptotic shapes of the solutions as  $\beta \rightarrow 0$  in the four cases are radically different.

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If  $r \equiv 1$  is constant, and there is a stable period 2 orbit  $\{a_1, a_2\}$  of the map  $x \rightarrow f(x)$ , one obtains a **square wave** of period  $2 + O(\beta)$ .

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The solution need not be unique, and need not be stable. The vertical parts of the wave have thickness  $O(\beta)$  and are described by transition layer equations.

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In contrast to the constant delay case, for small  $\beta$  the periodic solution is **unique** and **superstable** with asymptotic period

$$p = k + 1 + \frac{\beta |\log \beta|}{k - 1} + O(\beta).$$

Very detailed asymptotics are known for this solution as  $\beta \rightarrow 0$ .

TENSOR PRODUCTS, POSITIVE OPERATORS,  
AND DELAY-DIFFERENTIAL EQUATIONS

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## Ordinary Differential Equations

A linear ODE

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generates a **linear process** (solution map) in  $\mathbf{R}^n$

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namely a family of linear maps satisfying

$$T(t_0, t_0) = I, \quad T(t, t_1)T(t_1, t_0) = T(t, t_0)$$

for all  $t, t_0, t_1$ .

Letting  $\wedge$  denote the **exterior product**, define

$$T(t, t_0)^{\wedge m} = T(t, t_0) \wedge T(t, t_0) \wedge \cdots \wedge T(t, t_0)$$

for  $m \leq n$ .

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This was studied by J. Muldowney and Q. Wang in the case  $\dot{x} = A(t)x$  is the linearization around a solution

$$y = p(t) \quad \text{satisfying} \quad \dot{y} = f(y),$$

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They obtained information about the nonlinear equation  $\dot{y} = f(y)$ .

## Tensor Products

Let  $V$  and  $W$  be vector spaces. Then  $V \otimes W$  is the vector space generated by all elements  $v \otimes w$  (with  $v \in V$  and  $w \in W$ ) under the relations

$$\lambda(v \otimes w) = (\lambda v) \otimes w = v \otimes (\lambda w),$$

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Tensor product  $A \otimes B$  of linear maps  $A : V \rightarrow V$  and  $B : W \rightarrow W$ .

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The exterior product

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is the subspace generated by all elements

$$v_1 \wedge v_2 \wedge \cdots \wedge v_m = \frac{1}{m!} \sum_{\sigma \in \mathcal{S}_m} (-1)^\sigma v_{\sigma(1)} \otimes v_{\sigma(2)} \otimes \cdots \otimes v_{\sigma(m)},$$

for  $v_i \in V$  where  $\mathcal{S}_m$  is the symmetric group on  $m$  elements.

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## Spectral Properties

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## The Injective Tensor Product

The **injective norm**  $\|\cdot\|_{\varepsilon}$  on  $X \otimes Y$  is defined to be

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The resulting space is not in general complete, so we take its completion and obtain a new Banach space denoted  $X \otimes_\varepsilon Y$ .

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This extends to any (finite) number of factors, so

$$(C[-1, 0])^{\otimes m} = C([-1, 0]^m).$$

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$$\varphi(\theta_{\sigma(1)}, \theta_{\sigma(2)}, \dots, \theta_{\sigma(m)}) \equiv (-1)^\sigma \varphi(\theta_1, \theta_2, \dots, \theta_m)$$

holds identically for every  $\sigma \in \mathcal{S}_m$ .

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$$[T(1)\varphi](\theta) = \varphi(0) - \int_{-1}^{\theta} b(s+1)\varphi(s) ds$$

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Begin with  $\varphi \in (C[-1, 0])^{\wedge 2}$  and do the same. In this case **there will be cancellations in the final formula.**



$$\begin{aligned} & [T(1)^{\otimes 2}\varphi](\theta_1, \theta_2) \\ &= \varphi(0, 0) - \int_{-1}^{\theta_2} b(s+1)\varphi(0, s) ds \\ &\quad - \int_{-1}^{\theta_1} b(s+1)\varphi(s, 0) ds \\ &\quad + \int_{-1}^{\theta_1} \int_{-1}^{\theta_2} b(s+1)b(r+1)\varphi(s, r) dr ds. \end{aligned}$$

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If  $m$  is **even** the minus signs disappear.

$$\begin{aligned} [T(1)^{\wedge 2}\varphi](\theta_1, \theta_2) &= \int_{\theta_1}^{\theta_2} b(s+1)\varphi(s, 0) ds \\ &+ \int_{-1}^{\theta_1} \int_{\theta_1}^{\theta_2} b(s+1)b(r+1)\varphi(s, r) dr ds. \end{aligned}$$

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If  $b(t) \geq 0$  then the operator  $T(1)^{\wedge 2}$  (and more generally  $T(t, t_0)^{\wedge m}$  if  $m$  is **even**) is a positive operator with respect to a certain cone.

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$$K_* = \{\varphi \in (C[-1, 0])^{\wedge m} \mid \varphi(\theta_1, \theta_2, \dots, \theta_m) \geq 0$$

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The same conclusion holds if  $b(t) \leq 0$  and  $m$  is odd.

$$\begin{aligned}
& [T(1)^{\wedge m} \varphi](\theta_1, \dots, \theta_m) \\
&= \int_{\theta_1}^{\theta_2} \cdots \int_{\theta_{m-1}}^{\theta_m} b^1(s_1) \cdots b^1(s_{m-1}) \varphi(s_1, \dots, s_{m-1}, 0) ds_{m-1} \cdots ds_1 \\
&+ (-1)^m \int_{-1}^{\theta_1} \cdots \int_{\theta_{m-1}}^{\theta_m} b^1(s_0) \cdots b^1(s_{m-1}) \varphi(s_0, \dots, s_{m-1}) ds_{m-1} \cdots ds_0,
\end{aligned}$$

where  $b^1(s) = b(s + 1)$ .

We are taking  $a(t) \equiv 0$  for convenience.

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Then the Floquet multipliers  $\mu_j$  (spectrum of  $T(\gamma, 0)$ ) are infinite in number and satisfy

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Further, the Floquet solutions corresponding to  $\mu_{2k-1}$  and  $\mu_{2k}$  have **lap number**

$$V(x_t) \equiv 2k - 1.$$

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We wish to obtain a **computable lower bound** for this quantity, and hence for the individual multipliers  $|\mu_k|$ .

**Lemma.** Let  $L_1$  and  $L_2$  be linear operators for which

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Applying this lemma to  $M^{\wedge m}$ , in the case that  $b(t) \geq b_0 > 0$  and  $m$  is even, gives a computable lower bound

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for the magnitude of each characteristic multiplier. In fact we conclude that there are infinitely many characteristic multipliers.

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At the beginning of the homotopy ( $\kappa = 0$ ) we have a constant coefficient problem, and so the gap structure

$$|\mu_1| \geq |\mu_2| > |\mu_3| \geq |\mu_4| > |\mu_5| \geq |\mu_6| > \dots$$

and properties of the lap number hold.

Now consider the homotopy

$$\dot{x}(t) = -\kappa a(t)x(t) - [\kappa b(t) + (1 - \kappa)b_0]x(t - 1), \quad 0 \leq \kappa \leq 1.$$

The lower bounds  $|\mu_k| \geq C_k$  remain valid throughout the homotopy.

At the beginning of the homotopy ( $\kappa = 0$ ) we have a constant coefficient problem, and so the gap structure

$$|\mu_1| \geq |\mu_2| > |\mu_3| \geq |\mu_4| > |\mu_5| \geq |\mu_6| > \dots$$

and properties of the lap number hold.

These features are continued throughout the homotopy to  $\kappa = 1$ , using “pseudo-continuity” properties of the lap-number  $V(\cdot)$ .

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- ▶ The eigenvalue  $\lambda = r$  need not be simple nor the eigenvector  $v$  unique.
- ▶ Simplicity/uniqueness is related to “irreducibility” of the operator  $L$ .

$$\dot{x}(t) = -b(t)x(t-1), \quad b(t) \geq b_0 > 0,$$

We take  $m$  even, say  $m = 2$  for convenience. Recall and define

$$\begin{aligned} [T(1)^{\wedge 2}\varphi](\theta_1, \theta_2) &= \int_{\theta_1}^{\theta_2} b(s+1)\varphi(s, 0) ds \\ &\quad + \int_{-1}^{\theta_1} \int_{\theta_1}^{\theta_2} b(s+1)b(r+1)\varphi(s, r) dr ds, \end{aligned}$$

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Then  $T(1)^{\wedge 2} \geq cT_0^{\wedge 2}$  for some  $c > 0$ , and so

$$r(T(1)^{\wedge 2}) \geq cr(T_0^{\wedge 2})$$

for the spectral radii of these operators.

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**Theorem.** In the setting of the Kreĭn-Rutman Theorem, if additionally  $L$  is  $u_0$ -positive, then the eigenvalue  $r$  (the spectral radius) is algebraically simple.

# Regularity of Solutions of Delay-Differential Equations: Analyticity versus $C^\infty$

John Mallet-Paret  
Division of Applied Mathematics  
Brown University

## Regularity of Solutions

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But in general the answer is not so clear.

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It is known that  $x(t)$  has an analytic extension to the lower half-plane  $\operatorname{Im} t < 0$ .

We believe the real axis  $\operatorname{Im} t = 0$  is the boundary of the region where  $x(t)$  is analytic (holomorphic).

$$\dot{x}(t) = f(x(t), x(t-r)), \quad r = r(x(t)),$$

If  $f(u, v)$  and  $r(u)$  are analytic in  $u$  and  $v$ , then  $x(t)$  is  $C^\infty$  in  $t$ .

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Analyticity is **unknown** in general, and there is reason to believe  $x(t)$  is analytic for some  $t$  but not in general for all  $t$ .



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The dynamics of the “history” map

$$t \rightarrow \eta(t) = t - r(t)$$

plays a role in determining for which  $t$  the solution  $x(t)$  is analytic.

For a given  $C^\infty$  solution  $x(t)$  we distinguish two sets:

$$\mathcal{A} = \{t_0 \mid x(t) \text{ is analytic for } t \text{ in some neighborhood of } t_0\},$$

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Note that  $\mathcal{A} \subseteq \mathbf{R}$  is open and  $\mathcal{N} \subseteq \mathbf{R}$  is closed.

**Theorem.** Consider the equation

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$$\eta(\mathcal{N}) \subseteq \mathcal{N}, \quad \eta(\mathcal{A} \setminus \mathcal{M}) \subseteq \mathcal{A},$$

where  $\mathcal{M} \subseteq \mathbf{R}$  is the set of local minima and maxima of  $\eta(t)$ .



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Suppose  $x(t)$  is analytic in a neighborhood of  $t = t_1$ . Then  $x(\eta(t))$  is analytic near  $t = t_0$ . Regarding  $\beta(t)x(\eta(t))$  as a known forcing term in the differential equation, we conclude that  $x(t)$  is analytic near  $t = t_0$ .

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and so  $x(t)$  is analytic near  $t_1$ . ///



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**Idea of Proof.** Write the equation in integrated form and apply a standard contraction mapping argument in the space of functions analytic in a disc about  $t_0$ .

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This solution also satisfies the differential equation

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Suppose that  $\eta(0) = 0 \pmod{2\pi}$  and  $\dot{\eta}(0) = \mu > 1$ .

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where the series for  $\alpha(\tau)$  converges, but the series for  $y(\tau)$  need not. The coefficients  $y_n$  are uniquely determined by the recursion

$$\lambda(n+1)y_{n+1} = (1 - \mu^{n+1}) \sum_{k=0}^n \alpha_{n-k} y_k.$$

Define quantities  $w_n$  by

$$y_n = \left( \frac{(-1)^n \alpha_0^n M_n}{\lambda^n n!} \right) w_n, \quad M_n = \prod_{k=1}^n (\mu^k - 1) \sim \mu^{n(n+1)/2}.$$

Then

$$w_{n+1} = w_n + \sum_{k=0}^{n-1} (-1)^{n-k} \left( \frac{\lambda^n n!}{\alpha_0^n M_n} \right) \left( \frac{\alpha_0^k M_k}{\lambda^k k!} \right) \left( \frac{\alpha_{n-k}}{\alpha_0} \right) w_k$$

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If  $w_\infty = 0$  then there exists a unique analytic solution through  $\tau = 0$  (although there may exist other non-analytic solutions).

**Examples with  $w_\infty \neq 0$** 

Consider

$$\lambda x(t) = \int_{t+(\mu-1)\sin t-2\pi m}^t x(s) ds$$

where  $1 < \mu < 2\pi m + 1$ .

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One also must show that the Hartman-Grobman conjugacy  $\sigma(\tau) = \sigma(\tau, \mu)$  is well-behaved for large  $\mu$ .

## Coexistence of analyticity and non-analyticity

For the previous example with  $\eta(t) = t + (\mu - 1) \sin t - 2\pi m$ , for certain  $\mu$  there are points  $t_*$  at which

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## More on the Integral Equation

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Here we assume that

$r : \mathbf{R} \rightarrow \mathbf{R}$  is continuous (not necessarily analytic),

$$r(t) \geq 0, \quad r(t + 2\pi) = r(t),$$

for all  $t \in \mathbf{R}$ .

## Integral Operator

$$(Lx)(t) = \int_{\eta(t)}^t x(s) ds, \quad x \in X,$$

$$X = \{x : \mathbf{R} \rightarrow \mathbf{R} \mid \text{continuous and } 2\pi \text{ periodic}\}$$

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Then  $L : X \rightarrow X$  is a positive operator (with respect to the cone of nonnegative functions).

The Krein-Rutman Theorem implies there exists  $\lambda > 0$  and  $x \in X \setminus \{0\}$ , with  $x \geq 0$ , such that

$$Lx = \lambda x$$

if and only if the spectral radius  $\text{rad}(L)$  is positive. And if so, one can take  $\lambda = \text{rad}(L)$ .

**Theorem.** The spectral radius is positive,  $\text{rad}(L) > 0$ , if and only if

$$\inf_{s \geq t} \eta(s) < t \quad (*)$$

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**Remark.** If  $\eta(t) < t$  (that is,  $r(t) > 0$ ) for every  $t$ , then  $(*)$  holds and  $\text{rad}(L) > 0$ . In this case the eigenfunction is unique.

**Sketch of Proof.** Suppose  $(*)$  holds for every  $t$ . Using  $(*)$  we obtain points

$$t_0 < t_1 < t_2 < \cdots < t_m \equiv t_0 \pmod{2\pi}$$

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This implies (upon iterating) that  $\|L^n\| \geq c^n$ , and thus  $\text{rad}(L) \geq c > 0$ .

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Gronwall implies  $x(\tau) \equiv 0$  identically, a contradiction.///

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More generally, is it possible for  $L$  to have more than one positive eigenvalue?

Consider the case that  $r(t)$  has integer period  $m$  and

$$\eta(t) = k - c_k, \quad k < t < k + 1$$

where  $c_k = c_{k+m} > 0$  is an integer.

This leads to a problem for  $m \times m$  matrices  $\Gamma$  of the form

$$\Gamma = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 \end{pmatrix},$$

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Is it possible for such  $\Gamma$  to have more than one eigenvalue in  $(1, \infty)$ ?

Some numerical calculations suggest not.

We now come to a main result on the analyticity set  $\mathcal{A}$ .

**Theorem.** In addition to the standing assumptions (periodicity and nonnegativity) on  $r(t)$ , assume that

- ▶  $r(t)$  is analytic in  $t$ ,
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An example of a system satisfying the above conditions is given by

$$r(t) = \rho(1 - \cos t), \quad \rho > \rho_0.$$

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Study **invariant intervals**  $I = [a, b]$ , namely  $\eta(I) \subseteq I = \text{compact}$

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Do this with  $t_0 = a \in \mathcal{N}$ . Then  $\overline{S(a)} \subseteq \mathcal{N}$  is uncountable.

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Then the closure  $\overline{S(t_0)}$  is uncountable.

Do this with  $t_0 = a \in \mathcal{N}$ . Then  $\overline{S(a)} \subseteq \mathcal{N}$  is uncountable.

Iterate the points in  $\overline{S(a)}$  backwards to get them in a neighborhood of  $a \pmod{2\pi}$ , and of  $b$ .



## Components of $\mathcal{A}$

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Thus  $\mathcal{A}$  has infinitely many components near  $a$  (and near  $b$ ).

Can  $\mathcal{N}$  have nonempty interior?

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Answer unknown, but if so it would be very interesting: An interval where the solution is everywhere  $C^\infty$  but nowhere analytic.

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But the endpoints of  $I'$  are not points of analyticity. Thus

$$(0, \tau), (\pi - \tau, \pi) \subseteq \mathcal{A}, \quad 0, \tau, \pi - \tau, \pi \in \mathcal{N}$$

Take any other interval (connected component) of  $\mathcal{A}$ , say

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But **(\*\*)** is impossible due to a **stretching condition**.

In the complement (mod  $2\pi$ )  $S$  of  $I \cup I'$ , the map  $\eta$  satisfies:

If  $\eta^k(t) \in S$  for every  $k \geq 1$  then

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Thus if (\*\*) holds there exist  $k_1 < k_2 < k_3 < \dots$  such that

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which is impossible.

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A final argument shows that  $\mathcal{N}$  has no isolated points, and so  $\mathcal{N}$  is a generalized Cantor set.