Boundedness and quasi-periodic solutions in nonlinear oscillations

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J. Littlewood proposed to study the boundedness of solutions for

$$\frac{d^2x}{dt^2} + g(x) = p(t), \tag{1}$$

where g(x) satisfies xg(x) > 0, and p is continuous and periodic in t.

• Example:

$$\frac{d^2x}{dt^2} + x = \sin t.$$

- According to the growth of g as x → ∞, the equation (1) is divided into three cases.
- Superlinear: $g(x)/x \to +\infty$.
- Sublinear: $g(x)/x \to 0$.
- Semilinear: $0 < \kappa \le g(x)/x \le K < +\infty$.

• Moser(1973) proposed to study the same problem for

$$\frac{d^2x}{dt^2} + \alpha x + \beta x^3 = p(t),$$

where α, β are positive constants and *p* is continuous and periodic in *t*.

- The firts result obtained by G. Morris(1976), who proved the boundedness of solutions as well as the existence of quasi-periodic solutions for $\alpha = 0, \beta = 2$.
- R. Direckerhoff and E. Zehnder(1987) prove the same result for the following equation

$$\frac{d^2x}{dt^2} + x^{2n+1} + \sum_{j=0}^{2n} p_j(t) x^j = 0,$$

if p_i are smooth.

M. Levi(1991) studied the following equation

$$\frac{d^2x}{dt^2} + F(t,x) = 0,$$

where F is C^5 in t.

- Later, the smooth assumption on p_j are improved to C^2 by X. Yuan(1998,2017).
- B. Liu (1989, 1992) proved the boundedness of solutions for equation

$$\frac{d^2x}{dt^2} + \alpha(t)x + \beta x^3 = p(t)$$

for continuous α and p.

• The first result obtained by T. Kupper and J. You(1991), who proved the boundedness of solutions for the equation

$$\frac{d^2x}{dt^2} + |x|^{\alpha-1}x = p(t)$$

where $0 < \alpha < 1$, *p* is smooth.

• B, Liu(2001) extended this result to general case

$$\frac{d^2x}{dt^2} + g(x) = p(t),$$

where p is also smooth.

• Open question: is there an example for *p* is only continuous?

Semilinear case

- The boundedness problem is more subtle.
- The first result is due to R. Ortega(1996)
- The Boundedness is obtained by him for the equation

$$\frac{d^2x}{dt^2} + ax^+ - bx^- = 1 + \epsilon p(t) \tag{2}$$

where $a \neq b$ two positive constants, ϵ small parameter, p smooth.

• B. Liu(1998) studies the following equations

$$\frac{d^2x}{dt^2} + n^2x + \phi(x) = \rho(t), \tag{3}$$

where $\phi(x) \to \pm \infty$ as $x \to \pm \infty$, *p* smooth.

• There is no small parameter!

 Ortega(1999) also study the above equation (3) under the assumption that φ is bounded.

More precisely, he assume that $\phi(x)$ is piecewise linear function

$$\phi(x) = \begin{cases} -L, & x \leq -1, \\ Lx, & -1 \leq x \leq 1, \\ L, & x \geq 1. \end{cases}$$

He prove that if

$$\left|\frac{1}{2\pi}\int_0^{2\pi}p(t)e^{int}dt\right|<\frac{2L}{\pi}$$

then all solutions of (3) are bounded.

• B. Liu (1999) drop the Ortega's assumption on ϕ . Under the condition

$$\left|\frac{1}{2\pi}\int_{0}^{2\pi}p(t)e^{int}dt\right| < \frac{\phi(+\infty) - \phi(-\infty)}{\pi}$$
(4)

we get the same conclusion.

- The inequality (4) is called Lazer-Landesman condition.
- Open Problem: what is happened if

$$\left|\frac{1}{2\pi}\int_{0}^{2\pi}p(t)e^{int}dt\right|=\frac{\phi(+\infty)-\phi(-\infty)}{\pi}$$

• There is a result (B. Liu) for

$$\left|\frac{1}{2\pi}\int_0^{2\pi}p(t)e^{int}dt\right|=\frac{\phi(+\infty)-\phi(-\infty)}{\pi}=0.$$

 B. Liu(2004) also study the same problem when the function φ depend on time t.

Isochronous center: sigular case

 We(Capietto and Liu) study the existence of quasi-periodic solutions as well as boundedness of solutions for the equation

$$\frac{d^2x}{dt^2} + V_x(x) = p(t);$$

where *p* is a π -periodic function and, for x > -1

$$V(x) = \frac{1}{2}x_{+}^{2} + \frac{1}{(1-x_{-}^{2})^{\gamma}} - 1, \quad \gamma > 0.$$

 isochronous case: B. Liu(2009) considers the boundedness of solutions for isochronous center with singular potential function

$$\frac{d^2x}{dt^2}+V_x(x)+g(x)=p(t).$$

For example

$$V_x(x) = \frac{x+1}{4} - \frac{1}{4(1+x)^3}$$

• The lazer-Landesman condition

$$\lim_{\rho \to +\infty} \int_{0}^{2\pi} g(\rho \left| \sin \frac{t}{2} \right|) \left| \sin \frac{t}{2} \right| dt > \int_{0}^{2\pi} \rho(t+\theta) \left| \sin \frac{t}{2} \right| dt$$

is needed.

• What will be happened if the above inequality is violated?

Consider the mapping

$$\mathcal{M}: \quad \theta_1 = \theta + \alpha(r) + \epsilon f(\theta, r), \quad r_1 = r + \epsilon g(\theta, r),$$

where *f*, *g* are smooth functions and $\alpha' \neq 0$.

- Question: Under what conditions on f, g, the mapping \mathcal{M} has invariant curves.
- Example: g = 1, there is no invariant curves!
- Condition: \mathcal{M} is area-preserving.
- Moser(1962) proved the existence of invariant curves for *f* and *g* smooth.

Theorem

Assume that f and g are bounded in C^p (p > 3). Then there exists $\epsilon_0 > 0$ such that the mapping \mathcal{M} has an invariant curve in the domain $\mathbb{R} \times [a, b]$ if $0 < \epsilon < \epsilon_0$.

- This theorem can be used to prove the boundedness of solutions and the existence of quasi-periodic solutions for superlinear and sublinear cases.
- However, it seems that we cannot use it to study the same problem for semilinear equations.

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Ortega(1999) study the following mapping

$$\mathcal{M}_{\delta}: \begin{cases} \theta_1 = \theta + \beta + \delta l(\theta, r) + \delta f(\theta, r, \delta), \\ r_1 = r + \delta m(\theta, r) + \delta g(\theta, r, \delta), \end{cases} \quad (\theta, r) \in \mathbb{R} \times [a, b],$$

where the functions *l*, *m*, *f*, *g* are 2π -periodic in θ , $f(\theta, r, 0) = g(\theta, r, 0) = 0$, β is a constant, $0 < \delta < 1$ is a small parameter.

Theorem

Assume that $\beta/2\pi$ is irrational and $l(\cdot, \cdot), m(\cdot, \cdot), f(\cdot, \cdot, \delta), g(\cdot, \cdot, \delta) \in C^6$ and

$$\frac{1}{2\pi}\int_0^{2\pi}\frac{\partial l}{\partial r}(\theta,r)d\theta\neq 0.$$

Then there exists $\Delta_0 > 0$ such that the mapping \mathcal{M}_{δ} has an invariant curve in the domain $\mathbb{R} \times [a, b]$ if $0 < \delta < \Delta_0$.

Theorem

Assume that $\beta = 2n\pi$ and $l(\cdot, \cdot), m(\cdot, \cdot), f(\cdot, \cdot, \delta), g(\cdot, \cdot, \delta) \in C^6$; furthermore, suppose that

$$l>0, \quad \frac{\partial l}{\partial r}>0,$$

and there is a function $\Phi(\theta, r)$ such that

$$\Phi\in C^6,\quad \frac{\partial\Phi}{\partial r}>0,$$

$$l(\theta, r)\frac{\partial \Phi}{\partial \theta} + m(\theta, r)\frac{\partial \Phi}{\partial r} \equiv 0.$$

Then there exists $\Delta_0 > 0$ such that the mapping \mathcal{M}_{δ} has an invariant curve in the domain $\mathbb{R} \times [a, b]$ if $0 < \delta < \Delta_0$.

The above two theorems can be generalized to quasi-periodic mappings.

$$\mathcal{M}_{\delta}: \begin{cases} \theta_1 = \theta + \beta + \delta l(\theta, r) + \delta f(\theta, r, \delta), \\ r_1 = r + \delta m(\theta, r) + \delta g(\theta, r, \delta), \end{cases} \quad (\theta, r) \in \mathbb{R} \times [a, b],$$

where the functions *l*, *m*, *f*, *g* are quasi-periodic in θ with the frequency ω , $f(\theta, r, 0) = g(\theta, r, 0) = 0$, β is a constant, $0 < \delta < 1$ is a small parameter.

Theorem

Assume that $\omega_1, \omega_2, \cdots, \omega_n, 2\pi/\beta$ are rationally independent, $l(\cdot, \cdot), m(\cdot, \cdot), f(\cdot, \cdot, \delta), g(\cdot, \cdot, \delta) \in C^p \ (p > 2\tau + 1 > 2n + 1)$ and

$$\lim_{T\to\infty}\frac{1}{T}\int_0^T\frac{\partial l}{\partial r}(\theta,r)d\theta\neq 0.$$

Then there exists $\Delta_0 > 0$ such that the mapping \mathcal{M}_{δ} has an invariant curve in the domain $\mathbb{R} \times [a, b]$ if $0 < \delta < \Delta_0$. The invariant curve is quasi-periodic with the frequency ω .

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The functions I and m can be represented in the form

$$\begin{split} I(\theta,r) &:= \widetilde{I}(\theta,r) + \widetilde{I}(\theta,r) = \sum_{k \in \mathbb{Z}^n \setminus \mathbb{K}} l_k(r) e^{i \langle k, \omega \rangle \theta} + \sum_{k \in \mathbb{K}} l_k(r) e^{i \langle k, \omega \rangle \theta} \\ &= \sum_{k \in \mathbb{Z}^n \setminus \mathbb{K}} l_k(r) e^{i \langle k, \omega \rangle \theta} + \sum_{\ell \in \mathbb{Z}} l_{\ell k^0}(r) e^{(2j_0 \pi/\beta) i \ell \theta}, \end{split}$$

$$\begin{split} m(\theta,r) &:= \widetilde{m}(\theta,r) + \overline{m}(\theta,r) = \sum_{k \in \mathbb{Z}^n \setminus \mathbb{K}} m_k(r) e^{i\langle k, \omega \rangle \theta} + \sum_{k \in \mathbb{K}} m_k(r) e^{i\langle k, \omega \rangle \theta} \\ &= \sum_{k \in \mathbb{Z}^n \setminus \mathbb{K}} m_k(r) e^{i\langle k, \omega \rangle \theta} + \sum_{\ell \in \mathbb{Z}} m_{\ell k^0}(r) e^{(2j_0 \pi/\beta)i\ell \theta} \end{split}$$

 $\overline{I}(\theta + \beta, r) \equiv \overline{I}(\theta, r), \quad \overline{m}(\theta + \beta, r) \equiv \overline{m}(\theta, r).$

Theorem

• Suppose that the functions *I*, *m*, *f*, *g* satisfy

$$l(\cdot, \cdot) \in C^{p+2} \ (p > 2\tau + 1 > 2n + 1), \quad \overline{l}(\theta, r) > 0,$$

$$m(\cdot,\cdot), f(\cdot,\cdot,\delta), g(\cdot,\cdot,\delta) \in C^{p+1}.$$

• There is a function $L(\theta, r) \equiv L(\theta + \beta, r)$ satisfying

$$L \in C^{p+2}, \qquad \frac{\partial L(\theta, r)}{\partial r} > 0$$
 (5)

$$\overline{l}(\theta, r)\frac{\partial L}{\partial \theta}(\theta, r) + \overline{m}(\theta, r)\frac{\partial L}{\partial r}(\theta, r) \equiv 0,$$
(6)

and two numbers \tilde{a} and \tilde{b} such that

$$a < \widetilde{a} < \widetilde{b} < b$$

and

$$L_{\max}(a) < L_{\min}(\widetilde{a}) \le L_{\max}(\widetilde{a}) < L_{\min}(\widetilde{b}) \le L_{\max}(\widetilde{b}) < L_{\min}(b), \quad (7)$$

 $\frac{\partial \bar{l}(\theta, r)}{\partial r} > 0,$

$$L_{\min}(r) := \min_{\theta \in \mathbb{R}} L(\theta, r), \quad L_{\max}(r) := \max_{\theta \in \mathbb{R}} L(\theta, r).$$

Then there exists $\Delta_0 > 0$ such that if $\delta < \Delta_0$, the mapping \mathcal{M}_{δ} has an invariant curve which is quasi-periodic with the frequency $\omega = (\omega_1, \omega_2, \cdots, \omega_n)$. The constants Δ_0 depend only on *a*, *b*, \tilde{a}, \tilde{b} , $l(\theta, r), m(\theta, r)$ and $L(\theta, r)$.

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Consider the following equation

$$x'' + ax^+ - bx^- = f(t),$$
 (8)

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where *a*, *b* are two different positive constants, $x^+ = \max\{x, 0\}$, $x^- = \max\{-x, 0\}$, f(t) is smooth quasi-periodic function with the frequency $\omega = (\omega_1, \omega_2, \cdots, \omega_n)$.

Action and angle variables

Introduce a new variable y = x', then (8) is equivalent to the following planar system

$$\begin{cases} x' = y, \\ y' = -ax^+ + bx^- + f(t). \end{cases}$$
(9)

Let C(t) be the solution of the initial value problem

$$\begin{cases} x'' + ax^+ - bx^- = 0, \\ x(0) = 1, x'(0) = 0. \end{cases}$$

Then it is well known that $C(t) \in C^2(\mathbb{R})$ which can be given by

$$C(t) = \begin{cases} \cos \sqrt{a}t, & |t| \in [0, \frac{\pi}{2\sqrt{a}}], \\ -\sqrt{\frac{a}{b}}\sin \sqrt{b}(|t| - \frac{\pi}{2\sqrt{a}}), & |t| \in [\frac{\pi}{2\sqrt{a}}, \frac{\pi}{2\sqrt{a}} + \frac{\pi}{2\sqrt{b}}]. \end{cases}$$

Define S(t) be the derivative of C(t), then $S(t) \in C^1(\mathbb{R})$ and (i) C(-t) = C(t), S(-t) = -S(t). (ii) C(t) and S(t) are $2\omega_0\pi$ -periodic functions, $\omega_0 = \frac{1}{2}(\frac{1}{\sqrt{a}} + \frac{1}{\sqrt{b}})$. (iii) $S^2(t) + a(C^+(t))^2 + b(C^-(t))^2 \equiv a$. For r > 0, θ (mod 2π), we define the following generalized polar coordinates $T : (r, \theta) \to (x, y)$ as

$$\begin{cases} x = \varrho r^{\frac{1}{2}} C(\omega_0 \theta), \\ y = \varrho r^{\frac{1}{2}} S(\omega_0 \theta), \end{cases}$$

where $\rho = \sqrt{\frac{2}{a\omega_0}}$. It is easy to check that *T* is a symplectic transformation.

system (9) is changed into the following generalized polar coordinate system

$$\begin{cases} \theta' = \omega_0^{-1} - \frac{1}{2} \varrho C(\omega_0 \theta) f(t) r^{-\frac{1}{2}}, \\ r' = \omega_0 \varrho S(\omega_0 \theta) f(t) r^{\frac{1}{2}}. \end{cases}$$
(10)

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Now we change the role of the variable *t* and θ , and yields that

$$\begin{cases} \frac{dt}{d\theta} = \left[\omega_0^{-1} - \frac{1}{2}\varrho C(\omega_0\theta)f(t)r^{-\frac{1}{2}}\right]^{-1},\\ \frac{dr}{d\theta} = \omega_0 \varrho S(\omega_0\theta)f(t)r^{\frac{1}{2}} \left[\omega_0^{-1} - \frac{1}{2}\varrho C(\omega_0\theta)f(t)r^{-\frac{1}{2}}\right]^{-1}, \end{cases}$$
(11)

which is 2π -periodic in the new time variable θ . Let r_* be a positive number such that

$$\omega_0^{-1} - \frac{1}{2} \varrho r_*^{-\frac{1}{2}} |C|| |f| > 0.$$

System (11) is well defined for $r \ge r_*$. Let $(t(\theta), r(\theta))$ be a solution of (11) defined in a certain interval $I = [\theta_0, \theta_1]$ and such that $r(\theta) > r_*$ for all θ in *I*. The derivative $\frac{dt}{d\theta}$ is positive and the function *t* is a diffeomorphism from *I* onto $J = [t_0, t_1]$, where $t(\theta_0) = t_0$ and $t(\theta_1) = t_1$. The inverse function will be denoted by $\theta = \theta(t)$. It maps *J* onto *I*.

The Poincaré map P of (11) has the expansion

$$P: \begin{cases} t_1 = t_0 + 2\omega_0 \pi + \frac{1}{2}\omega_0^2 \rho r_0^{-\frac{1}{2}} \int_0^{2\pi} C(\omega_0 \theta) f(t_0 + \omega_0 \theta) d\theta + O(r_0^{-1}), \\ r_1^{\frac{1}{2}} = r_0^{\frac{1}{2}} + \frac{1}{2}\omega_0^2 \rho \int_0^{2\pi} f(t_0 + \omega_0 \theta) S(\omega_0 \theta) d\theta + O(r_0^{-\frac{1}{2}}). \end{cases}$$

Assume that f has the following Fourier series

$$f(t) = \sum_{k} f_k e^{i\langle k,\omega\rangle t}$$

$$L(t_0) = \int_0^{2\pi} f(t_0 + \omega_0 \theta) C(\omega_0 \theta) d\theta \neq 0, \text{ for all } t_0 \in \mathbb{R}, \quad (12)$$

Theorem

If $f(t) \in C^p$ (p > 2n + 1) satisfies (12), $\langle k, \omega \omega_0 \rangle \notin \mathbb{Z}$ for any $k \in \mathbb{Z}^n \setminus \{0\}$. Then system (9) has infinitely many quasi-periodic solutions and all solution are bounded.

Theorem

If $f(t) \in C^p$ (p > 2n + 3) satisfies (12), $\langle k, \omega \omega_0 \rangle \in \mathbb{Z}$ for some $k \in \mathbb{Z}^n$. Denote by \mathbb{K} the lattice of \mathbb{Z}^n such that $\langle k, \omega \omega_0 \rangle \in \mathbb{Z}$ for $k \in \mathbb{K}$ and $\langle k, \omega \omega_0 \rangle \notin \mathbb{Z}$ for $k \notin \mathbb{K}$, by $f_{\mathbb{K}}(t)$ the function

$$f_{\mathbb{K}}(t) = \sum_{k \in \mathbb{K}} f_k e^{i \langle k, \omega
angle t}$$

Moreover, if

$$\Phi_{\mathbb{K}}(t_0) = \frac{\omega_0^2 \varrho}{2} \int_0^{2\pi} f_{\mathbb{K}}(t_0 + \omega_0 \theta) C(\omega_0 \theta) d\theta \neq 0, \quad \text{for all} \quad t_0 \in \mathbb{R}.$$

Then system (9) has many quasi-periodic solutions and all solutions are bounded.

Thank you!